

## CLAIMS

- Sub Q1
1. A camera comprising:
    - 2 a camera lens;
    - 3 acquisition circuitry receiving images via said camera lens, for acquiring a first
    - 4 field of view when said camera lens is in a first orientation and for acquiring a second
    - 5 field of view when said camera lens is in a second orientation; and
    - 6 a viewfinder displaying the second field of view when said camera lens is in
    - 7 the second orientation and displaying at least a portion of the first field of view at least
    - 8 partially composited with the second field of view.
  - 1 2. The camera of claim 1 wherein the second field of view at least partially
  - 2 overlaps the first field of view.
  - 1 3. The camera of claim 1 wherein a size of the at least a portion of the first field
  - 2 of view is prescribed.
  - 1 4. The camera of claim 3 wherein the size of the at least a portion of the first field
  - 2 of view is prescribed relative to a size of the first field of view.
  - 1 5. The camera of claim 3 wherein the size of the at least a portion of the first field
  - 2 of view is prescribed relative to a size of the second field of view.
  - 1 6. The camera of claim 5 wherein the size of the at least a portion of the first field
  - 2 of view is its width, and the size of the second field of view is its width.

1 7. The camera of claim 5 wherein the size of the at least a portion of the first field  
2 of view is its height, and the size of the second field of view is its height.

1 8. The camera of claim 5 wherein the size of the at least a portion of the first field  
2 of view is the field of view angle it subtends, and the size of the second field of view  
3 is the field of view angle it subtends.

1 9. The camera of claim 5 wherein the size of the at least a portion of the first field  
2 of view is prescribed to an amount between 20% and 40% of the size of the second  
3 field of view.

1 10. The camera of claim 1 wherein the at least a portion of the first field of view is  
2 composited with the second field of view by an opacity of approximately 50%.

1 11. The camera of claim 1 wherein the at least a portion of the first field of view is  
2 composited with the second field of view by an opacity of approximately 100%.

1 12. The camera of claim 1 wherein the focus of said camera lens is not changed  
2 during acquisition of the first and second fields of view.

1 13. The camera of claim 1 further comprising a lens focus lock for locking the  
2 focus of said camera lens during acquisition of the first and second fields of view.

1 14. The camera of claim 1 further comprising combining circuitry for combining  
2 the first and second fields of view.

1 15. The camera of claim 14 wherein the first and second fields of view are portions  
2 of a scene and wherein said combining circuitry combines the first and second fields  
3 of view into a panoramic image of the scene.

4 16. The camera of claim 15 wherein said panoramic image has a cylindrical  
5 geometry.

1 17. The camera of claim 16 further comprising rectilinear-to-cylindrical  
2 conversion circuitry for converting the first and second fields of view from rectilinear  
3 coordinates to cylindrical coordinates.

1 18. The camera of claim 15 wherein said panoramic image has a spherical  
2 geometry.

1 19. The camera of claim 15 further comprising rectilinear-to-spherical conversion  
2 circuitry for converting the first and second fields of view from rectilinear coordinates  
3 to spherical coordinates.

1 20. The camera of claim 15 further comprising view control circuitry for selecting  
2 a portion of the panoramic image to display, and wherein said viewfinder displays the  
3 selected portion of the panoramic image.

1 21. The camera of claim 20 wherein said panoramic image has a cylindrical  
2 geometry and further comprising cylindrical-to-rectilinear conversion circuitry for  
3 converting the selected portion of the panoramic image from cylindrical coordinates to  
4 rectilinear coordinates.

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1 76. The camera of claim 73 wherein said color alignment circuitry also adjusts the  
2 color values at multiple pixel locations within the second frame based on the  
3 brightness and contrast parameters.

1 77. The camera of claim 76 wherein said color alignment circuitry applies opposite  
2 brightness and contrast adjustments to the first and second frames.

1 78. The camera of claim 67 further comprising color alignment circuitry for  
2 adjusting the color values at multiple pixel locations within the second frame based on  
3 the brightness and contrast parameters.

1 79. The camera of claim 78 wherein said color alignment circuitry applies 100% of  
2 the brightness and contrast parameters within a region of overlap of the first frame and  
3 the second frame.

1 80. The camera of claim 78 wherein said color alignment circuitry applies  
2 approximately 75% of the brightness and contrast parameters within a region of  
3 overlap of the first frame and the second frame.

1 81. The camera of claim 54 further comprising stitching circuitry for compositing  
2 a portion of the second frame onto a portion of the first frame.

1 82. The camera of claim 81 wherein said stitching circuitry replaces color values at  
2 multiple pixel locations within the first frame with values that are weighted averages  
3 of color values in the first frame and color values in the second frame.

1 83. The camera of claim 54 wherein data strips from the first and second frames  
2 are incrementally stored within the panoramic image as the frames are at least partially  
3 combined.

1 84. The camera of claim 83 further comprising a far edge delimiter and a near edge  
2 delimiter and wherein data from a portion of the first frame between said far edge  
3 delimiter and said near edge delimiter is stored within the panoramic image.

1 85. The camera of claim 54 wherein said acquisition circuitry acquires at least one  
2 additional frame with said camera lens being in at least one additional orientation, and  
3 wherein said combining circuitry at least partially combines the at least one additional  
4 frame into the panoramic image.

1 86. The camera of claim 85 further comprising motion estimation circuitry located  
2 within said camera housing for determining horizontal and vertical offsets for spatially  
3 aligning two selected acquired frames.

1 87. The camera of claim 86 wherein said motion estimation circuitry comprises  
2 sum-of-absolute-difference circuitry for summing absolute values of color differences  
3 between the two selected acquired frames at a multiplicity of pixel locations.

1 88. The camera of claim 85 further comprising color blending circuitry for  
2 determining brightness and contrast parameters for chromatically aligning two  
3 selected acquired frames.



1 95. The camera of claim 93 wherein said panoramic image has a spherical  
2 geometry and further comprising spherical-to-rectilinear conversion circuitry for  
3 converting the selected portion of the panoramic image from spherical coordinates to  
4 rectilinear coordinates prior to display thereof.

1 96. A camera comprising:  
2 a camera lens;  
3 a memory for storing data for a panoramic image;  
4 a display for displaying at least a portion of the panoramic image; and  
5 display control circuitry for selecting a portion of the panoramic image to  
6 display.

1 97. The camera of claim 96 wherein said panoramic image has a cylindrical  
2 geometry and further comprising cylindrical-to-rectilinear conversion circuitry for  
3 converting the selected portion of the panoramic image from cylindrical coordinates to  
4 rectilinear coordinates prior to display thereof.

1 98. The camera of claim 97 wherein said cylindrical-to-rectilinear conversion  
2 circuitry comprises line processing circuitry for computing converted color values at  
3 pixel locations within a vertical line of said display.

1 99. The camera of claim 98 wherein said line processing circuitry computes  
2 converted color values at pixel locations within a vertical line of the display based on  
3 non-converted color values along a corresponding vertical line in the selected portion  
4 of the panoramic image.





1 107. The camera of claim 106 wherein said at least one display control button  
2 includes at least one navigational panning button for navigation through the panoramic  
3 image in at least one direction.

1 108. The camera of claim 96 wherein said display control circuitry also selects a  
2 magnification factor for the selected portion of the panoramic image, and wherein said  
3 display displays the selected portion of the panoramic image at the selected  
4 magnification factor.

1 109. The camera of claim 108 wherein said display control circuitry is responsive to  
2 changes in focus of said camera lens.

1 110. The camera of claim 108 further comprising at least one view magnification  
2 button for zooming in and out of the panoramic image, and wherein said display  
3 control circuitry is responsive to pressing of said at least one view magnification  
4 button.

1 111. A method for combining a first frame and a second frame, comprising the steps  
2 of:

3 determining horizontal and vertical offsets for spatially aligning the first and  
4 second frames, comprising the step of summing absolute values of color differences  
5 between the first frame and the second frame at a multiplicity of pixel locations, based  
6 on trial values for horizontal and vertical offsets;

7 further determining brightness and contrast parameters for chromatically  
8 aligning the first and second frames; and

9 generating a panoramic image, comprising the step of compositing a portion of  
10 the second frame onto a portion of the first frame, based on the horizontal and vertical  
11 offsets and based on the brightness and contrast parameters.

1 112. The method of claim 111 wherein said summing step comprises the steps of:  
2 computing partial sums of absolute values of color differences between the  
3 first frame and the second frame at pixel locations within horizontal lines, based on the  
4 trial values for horizontal and vertical offsets; and  
5 accumulating the partial sums to form a complete sum of absolute values of  
6 color differences between the first frame and the second frame at a multiplicity of  
7 pixel locations.

1 113. The method of claim 112 further comprising the steps of:  
2 repeating said steps of computing and accumulating for a multiplicity of trial  
3 values for horizontal and vertical offsets; and  
4 selecting horizontal and vertical offsets from among the multiplicity of trial  
5 values for horizontal and vertical offsets, based on the respective complete sums.

1 114. The method of claim 113 wherein said selecting step selects horizontal and  
2 vertical offsets corresponding to a smallest local minimum value from among the  
3 complete sums.

1 115. The method of claim 111 further comprising the step of spatially aligning the  
2 first and second frames based on the horizontal and vertical offsets.

1 116. The method of claim 111 wherein said further determining step comprises the  
2 step of calculating means and variances of color values at a multiplicity of pixel  
3 locations within the first and second frames.

1 117. The method of claim 116 wherein said further determining step determines the  
2 brightness and contrast parameters in such a way that a mean and variance of color  
3 values at multiple pixel locations within the first frame are equal to the respective  
4 mean and variance of color values at corresponding multiple pixel locations within the  
5 second frame.

6 118. The method of claim 111 further comprising the step of chromatically aligning  
7 the first and second frames based on the brightness and contrast parameters.

1 119. The method of claim 111 wherein said compositing step comprises replacing  
2 color values at multiple pixel locations within the first frame with values that are  
3 weighted averages of color values in the first frame and color values in the second  
4 frame.

1 120. The method of claim 111 wherein at least one additional frame is combined  
2 with the first and second frames, the method further comprising the step of repeating  
3 said steps of determining, further determining and generating at least once for  
4 subsequent first and second frames from among the first and second and at least one  
5 additional frames.

1 121. The method of claim 120 further comprising the step of spatially aligning the  
2 at least one additional frame with another frame from among the first and second and  
3 at least one additional frames, based on the horizontal and vertical offsets.

1 122. The method of claim 120 further comprising the step of chromatically aligning  
2 the at least one additional frame with another frame from among the first and second  
3 and at least one additional frames, based on the brightness and contrast parameters.

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